

NP Completeness

Tao Hou

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- Previously, for different problems we consider, we were trying to show how we *can* design efficient algorithms for solving them
- Now, we are going to show for certain problems, how we *cannot* design efficient algorithms

Hard vs. Easy Problems

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 - ▶ There are also problems that can be solved in finite steps (e.g., in exponential time), but not in polynomial time
- Generally, we think of problems that are solvable by polynomial-time algorithms as being **tractable**, or “easy”, and problems that require superpolynomial time as being **intractable**, or “hard”

- The subject of this chapter, however, is an interesting class of problems called the “NP-complete” problems, whose status is unknown:
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- This so-called $P \neq NP$ question has been one of the deepest, most perplexing open research problems in theoretical computer science since it was first posed in 1971
- Notice that NP-complete problems are still in general considered “hard” problems as most people believe you cannot find polynomial time algorithms for them

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Euler tour vs. Hamiltonian cycle:

- An **Euler tour** of an undirected graph is a cycle that traverses each edge of the graph exactly once (it is allowed to visit vertices more than once)
- A **Hamiltonian cycle** of an undirected graph is a simple cycle that traverses each vertex exactly once
- We can determine whether a graph has an Euler tour in only $O(|E|)$ time
- Determining whether an undirected graph has a Hamiltonian cycle is NP-complete

Throughout this topic, we shall consider three classes of problems:

- **P**: Problems that are solvable in polynomial time
- **NP**: Problems that are “verifiable” in polynomial time
 - ▶ We have $P \subseteq NP$
- **NPC**: NP-complete problems, those problems that are as hard as **any** problems in the class NP (you can also say is the hardest problem in NP)

Understanding NP-completeness theory is critical to algorithm designers:

- If you can find that a problem is NP-complete, you would then do better to spend your time finding an approximation algorithm or solving a tractable special case
- Many natural and interesting problems that on the surface seem no harder than sorting, graph searching, or network flow are in fact NP-complete

Why do we care polynomial time?

We focus on polynomial time algorithms for certain reasons:

- Although a polynomial running time of $\Theta(n^{100})$ is completely disastrous in practice, the polynomial-time algorithms we actually encountered ***typically require much less time***
- Experience has shown that once the first polynomial-time algorithm for a problem has been discovered, ***more efficient algorithms often follow***

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 - ▶ E.g., a “serial random-access machine” model we typically assume, or an “abstract Turing machine” model
- Most importantly, the class of polynomial-time solvable problems has nice ***closure properties***, since polynomials are closed under addition, multiplication, and composition
 - ▶ E.g., if we apply a polynomial-time algorithm for polynomially many times, we still have a polynomial-time algorithm

Decision Problems vs. Optimization Problems

- Many problems of interest are *optimization* problems: each legal solution has an associated value, and we wish to find a legal solution with the best value
- (Example) SHORTEST-PATH-OPTMZ: given an undirected graph G and vertices u and v , we wish to find a path from u to v with the fewest edges

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- (Example) SHORTEST-PATH-OPTMZ: given an undirected graph G and vertices u and v , we wish to find a path from u to v with the fewest edges
- However, the theory of NP-Completeness focuses only on **decision** problems: given an input, a program should produce “yes” or “no”
- (Example) SHORTEST-PATH: given an undirected graph G , two vertices u and v , and **an integer** k , is there a path from u to v with $\leq k$ edges?

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 - ▶ E.g., given an instance (G, u, v, k) of SHORTEST-PATH, we can find the length ℓ of the shortest path of (G, u, v) using an algorithm for the optimization problem, and then check if $k \geq \ell$

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 - ▶ If we can find a polynomial-time algorithm for the optimization problem, we can definitely find a polynomial-time algorithm for the decision problem
 - ▶ Equivalently, if we **cannot** find a polynomial-time algorithm for the decision problem, we **also cannot** find a polynomial-time algorithm for the optimization problem
- Thus, though NP-completeness theory restricts attention to decision problems, it **often has implications for optimization problems**

Formal Definition of *Problems*

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- Return ...

Polynomial-time solvable problem

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Complexity class \mathcal{P}

The complexity class \mathcal{P} is the set of decision problems that are polynomial-time solvable

Consider two problems:

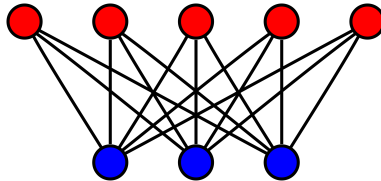
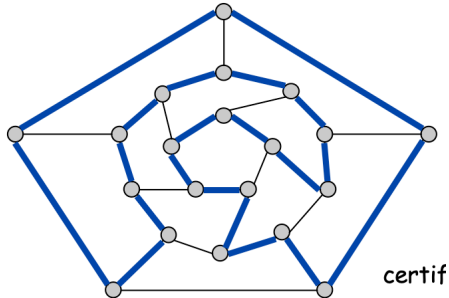
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Left dodecahedron graph (taken from [K&T] slides) has a Hamiltonian cycle while the right bipartite graph (taken from Wikipedia) does not have one

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A boolean formula is made up of the boolean variables x_1, \dots, x_n , operators including \wedge (AND), \vee (OR), \neg (NOT), \rightarrow (implication), \leftrightarrow (if and only if), and composite (combinations) of them possibly with parenthesis. E.g.,:

$$((x_1 \rightarrow x_2) \vee \neg((\neg x_1 \leftrightarrow x_3) \vee x_4)) \wedge \neg x_2.$$

- The two problems are “hard” to solve *directly* in the sense that no one on this earth has come up with a polynomial-time algorithm for them (although no one ever has proven otherwise)

Certificates and Verifiers

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- Let’s consider an easier version for such a problem by solving it “**indirectly**” (HAM-CYCLE as an example)
- Suppose that someone tells you a given graph G is Hamiltonian and offers to prove it **by giving you a sequence of vertices** which this person claims to be a Hamiltonian cycle
- It would then be easy to **verify** this: simply verify whether the sequence contain all the vertices and whether each two consecutive vertices form an edge

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- It would then be easy to **verify** this: simply verify whether the sequence contain all the vertices and whether each two consecutive vertices form an edge
- The “verification” process can definitely be done in polynomial time in terms of the size of G
- Formally speaking, the algorithm used for the “verification” is termed as a **verification algorithm**, and the sequence of vertices you used for verification is called a **certificate**

Verification algorithm

For a problem Q , a **verification algorithm** (or simply **verifier**), denoted $C(x, y)$, is an algorithm satisfying:

- $C(x, y)$ returns “yes”/“no”
- input x is an instance of Q
- input $y \in \{0, 1\}^*$ (a binary string) is a **certificate**
- x is an “yes”-instance of $Q \Leftrightarrow$ there exist a certificate y making $C(x, y)$ return “yes”

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Notice:

- For a “yes”-instance x , it's okay that $C(x, y)$ returns “no” given some certificate y
- As long as **there is one certificate** y making $C(x, y)$ return “yes”, it is fine
- But if x is a “no”-instance, then $C(x, y)$ should return “no” **for all certificates**

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- You first “**decode**” the certificate y (which is a binary string) into something “meaningful”
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(**Example**) A verification algorithm $C(x, y)$ for SAT:

- Notice that here x is a boolean formula with boolean variables x_1, \dots, x_n
- Given y as a bit string, decode y into a T/F assignment to x_1, \dots, x_n
 - ▶ The simplest thing to do is to take the first n bits in y and take them as the T/F assignment to x_1, \dots, x_n
 - ▶ If y has less than n bits, return “no”
- Then use the T/F assignment of x_1, \dots, x_n from the certificate y to verify whether the boolean formula evaluate to true; If true, return “yes”; otherwise, return “no”

(Example) A verification algorithm $C(x, y)$ for HAM-CYCLE:

- Given y as a bit string, decode y into a sequence of n vertices where n is the number of vertices in the input graph $G := x$
 - ▶ If y cannot be decoded into n vertices, return “no”
 - ▶ Ignore the remaining bits
- Then verify whether the n vertices form a valid Hamiltonian cycle

The Complexity Class **NP**

The complexity class **NP** is a set of decision problems such that a problem $Q \in \mathbf{NP}$ if and only if there is a verification algorithm $C(x, y)$ for Q running in polynomial time in term of the size of the Q 's instance x

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Example: SAT, HAM-CYCLE $\in \mathbf{NP}$

- There is one complexity class ***NPC*** which is yet to be defined
- Roughly saying, ***NPC*** is the set of “hardest” problems in ***NP***
- But to do that, we need a way to compare the “difficulty” of problems
- For that, we introduce the notion of “***reducibility***”, which is probably the single most important notion in the topic

Polynomial reduction

A decision problem Q_1 is said to **polynomially reduces** to (or simply **reduces** to) another decision problem Q_2 if there is a polynomial time ($O(|x_1|^k)$) algorithm \mathcal{F} taking an instance x_1 for Q_1 and computing an instance x_2 for Q_2 such that:

- x_1 is a “yes”-instance for Q_1 iff x_2 is a “yes”-instance for Q_2

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(**Implications**) If Q_1 polynomially reduces to Q_2 :

- Q_1 is “no harder” than Q_2 in the sense that
- Any polynomial-time algorithm \mathcal{A} for Q_2 can be used to solve Q_1 in polynomial-time, by doing:
 - ▶ Given an instance x_1 of Q_1 , use \mathcal{F} to compute an instance x_2 of Q_2
 - ▶ Then use \mathcal{A} to decide whether x_2 is a “yes”-instance for Q_2
 - ▶ Return “yes” if \mathcal{A} returns “yes”, and return “no” if \mathcal{A} returns “no”,
- So if Q_2 can be solved in polynomial time, then Q_1 also can

So whether a problem Q_1 reduces to another problem Q_2 completely relies on whether you can find a “reduction algorithm” \mathcal{F}

Example:

- Q_1 : Given a string x_1 , does x_1 contain the letter “a”?
- Q_2 : Given a string x_2 , does x_2 contain the letter “b”?

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- Q_2 : Given a string x_2 , does x_2 contain the letter “b”?
- Q_1 reduces to Q_2 with the reduction algorithm: given an instance x_1 of Q_1 , replace each occurrence of “a” in x_1 with “b” and each occurrence of “b” in x_1 with “a” and produce an instance x_2 of Q_2

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proof:

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- Let Q be a problem in P
- Then there is an algorithm \mathcal{A} solving Q in polynomial time
- To show that $Q \in NP$, we only need to design a polynomial-time verifier $C(x, y)$ for Q
- To do this, in C , we only need to invoke \mathcal{A} on x , and return the answer of \mathcal{A} (certificate y is completely ignored)

- The biggest question in CS: Is $P = NP$?
- This question was raised in the 1970's, and there is not an answer till this day
- The common belief is that $P \neq NP$
- The key lies in those NP-Complete problems, because if you can find an algorithm for a single NP-Complete problem, then all problems in NP , including all the other NP-Complete problems, can be solved in polynomial time (so $P = NP$)
- However, there are tons of NP-Complete problems out there, and **no one** has ever found a polynomial-time algorithm **for any of them** till this day

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proof:

- Let Q be an NP-Complete problem and let \mathcal{A} be a polynomial-time algorithm for Q
- Let Q' be an arbitrary problem in NP
- Since Q' reduces to Q , we have a polynomial-time reduction algorithm \mathcal{F} from Q' to Q
- Then we can have a polynomial-time algorithm for Q' : given an instance x' of Q' , compute an instance x of Q using the algorithm \mathcal{F} , then you just return whatever \mathcal{A} returns on x

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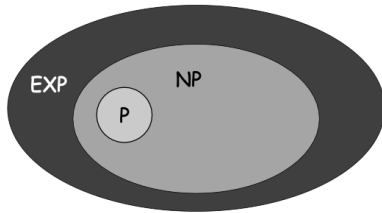
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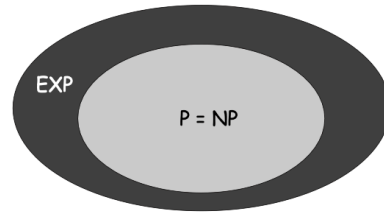
proof:

- Let *Q* be a problem in *NP* with a verifier $C(x, y)$
- Given an instance *x* of *Q*, we enumerate all possible certificates for *x* and see whether there is one certificate *y* making $C(x, y)$ return “yes”
- If there is such a certificate, we return “yes” for *x*, otherwise, we return “no”
- Notice that we only need to enumerate certificates of up to a size $m = poly(|x|)$, because any certificate beyond size *m* will not be helpful to us (see the “decoding” process for certificates)
- Total time would be $2^{poly(|x|)} f(|x|)$, where $f(|x|)$ is the time complexity of $C(x, y)$

The million-dollar question



If $P \neq NP$



If $P = NP$

(Figure from [K&T] slides)

- The term “NP” does not stand for “non-polynomial time” (we don’t know whether these problems can or cannot be solved in polynomial time)
- It stands for “non-deterministic polynomial-time solvable” (the verification algorithm we write is indeed a “non-deterministic algorithm”)
- As mentioned, if you have shown that a problem is NP-complete, then you should do something else rather trying to find a polynomial-time algorithm for it
- But people on this planet *haven’t proved* that an NP-Complete problem does not have a polynomial-time algorithm
- Only that people believe so because there are tons of NP-Complete problems and no one has ever found a polynomial-time algorithm for *any* of them

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 - So the general strategy for showing a problem Q to be NP-hard is to first find a problem Q^* known to be NP-hard, and then reduce Q^* to Q